



## *2. The Envelope Theorem*



$$V(\mathbf{a}) = \max_{\mathbf{x} \in R^n} f(\mathbf{x}, \mathbf{a}) \quad \text{s.t.} \quad g(\mathbf{x}, \mathbf{a}) = 0 \quad \mathbf{x} = (x_1, \dots, x_n)$$
$$\mathbf{a} = (a_1, \dots, a_j)$$

*The Envelope theorem states that for every  $\mathbf{a} \in U$ ,*

$$\frac{\partial V(\mathbf{a})}{\partial a_j} = \frac{\partial L}{\partial a_j} \Big|_{\mathbf{x}(\mathbf{a}), \lambda(\mathbf{a})} \quad j = 1, \dots, m$$



## ***Proof***

*Form the Lagrangian for the maximisation problem*

$$L \equiv f(\mathbf{x}, \mathbf{a}) + \lambda[g(\mathbf{x}, \mathbf{a})]$$

*For every  $\mathbf{a} \in U$*

$$\frac{\partial f(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial x_i} + \lambda(\mathbf{a}) \frac{\partial g(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial x_i} = 0$$

$$g(\mathbf{x}(\mathbf{a}), \mathbf{a}) = 0$$

①



If we evaluate this derivative at the point  $(\mathbf{x}(\mathbf{a}), \lambda(\mathbf{a}))$

$$\left. \frac{\partial L}{\partial a_j} \right|_{\mathbf{x}(\mathbf{a}), \lambda(\mathbf{a})} = \frac{\partial f(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial a_j} + \lambda(\mathbf{a}) \frac{\partial g(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial a_j} \quad (2)$$

We begin by directly differentiating  $V(\mathbf{a})$  with respect to  $a_j$ . Because  $a_j$  affects  $f$  directly and indirectly through its influence on each variable  $x_i(\mathbf{a})$

$$\frac{\partial V(\mathbf{a})}{\partial a_j} = \sum_{i=1}^n \left[ \frac{\partial f(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial x_i} \bullet \frac{\partial x_i(\mathbf{a})}{\partial a_j} \right] + \frac{\partial f(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial a_j}$$



*Go back to the first-order conditions, substituting into the bracketed term of the summation.*

$$\frac{\partial V(\mathbf{a})}{\partial a_j} = -\lambda(\mathbf{a}) \sum_{i=1}^n \left[ \frac{\partial g(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial x_i} \bullet \frac{\partial x_i(\mathbf{a})}{\partial a_j} \right] + \frac{\partial f(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial a_j} \quad \textcircled{3}$$



*Go back again to the first-order conditions ①  
and look at the second identity in the system.*

$$\because g(\mathbf{x}(\mathbf{a}), \mathbf{a}) = 0$$

$$\Rightarrow \sum_{i=1}^n \left[ \frac{\partial g(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial x_i} \bullet \frac{\partial x_i(\mathbf{a})}{\partial a_j} \right] + \frac{\partial g(\mathbf{x}(\mathbf{a}), \mathbf{a})}{\partial a_j} = 0$$

$$\therefore \frac{\partial V(\mathbf{a})}{\partial a_j} = \frac{\partial L}{\partial a_j} \Big|_{\mathbf{x}(\mathbf{a}), \lambda(\mathbf{a})}$$